

Numerical Model to Simulate Drift Trajectories of Large Vessels

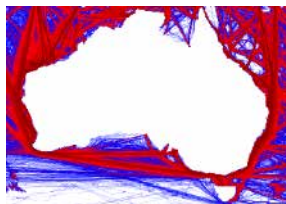
Simon Mortensen, HoD Marine DHI Australia



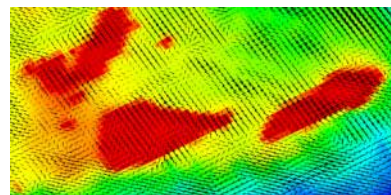
Conceptual framework - multi-layered risk estimation



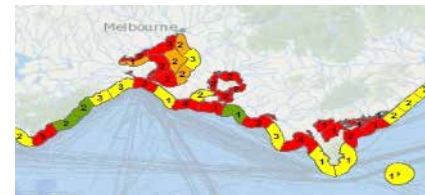
Layer 1 (2011):
Ship specific risk
(proxy for safety quality)



Layer 2 (2013/14/15):
Eg. Nm travelled, days in area, other
metric (proxy for vessel traffic
densities and/or exposure)

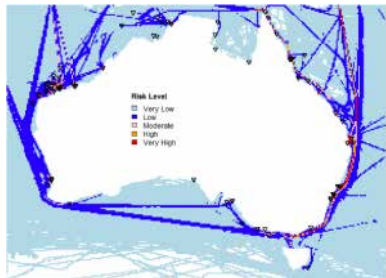


Layer 3 (2014/15): DHI
Physical environmental
layer (wind, waves, currents,
bathymetry)

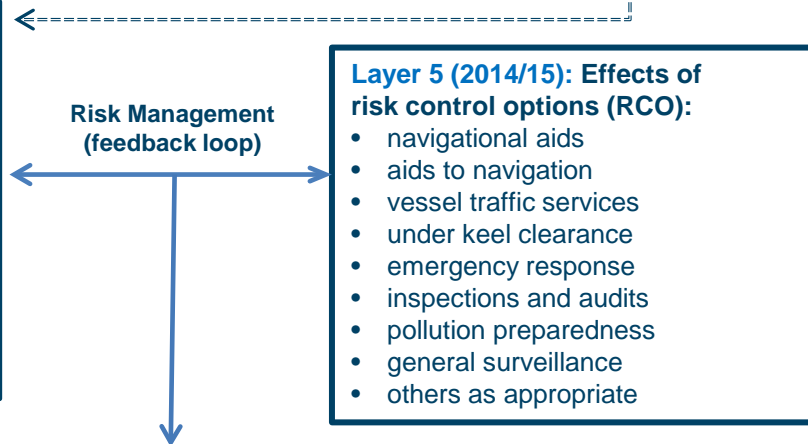


Layer 4 (2013):
Sensitivities (economic,
cultural/social, ecological)

Total Risk Exposure: Protect: property, life and marine environment

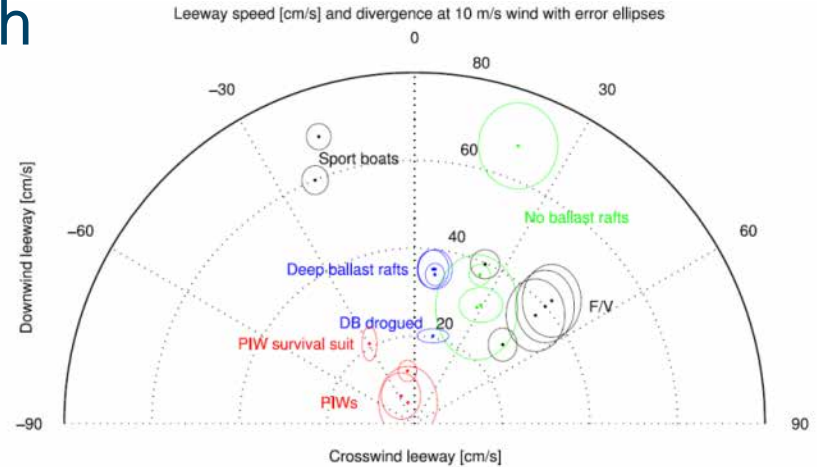
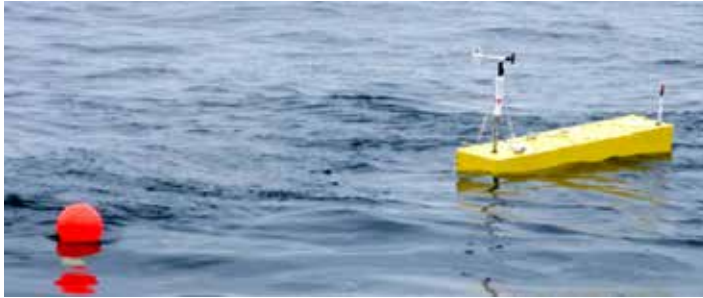


- Expressed as:
- probabilities
 - expected numbers
 - monetary value at risk (proxy to consequences)
 - oil on water
 - oil on coast



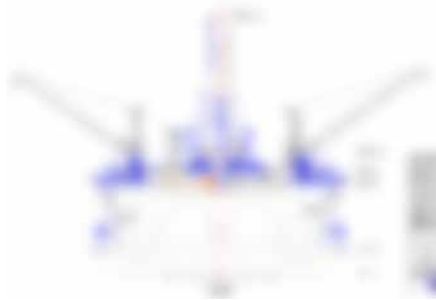
(Acceptable) residual risk

Limitations of Existing Approach

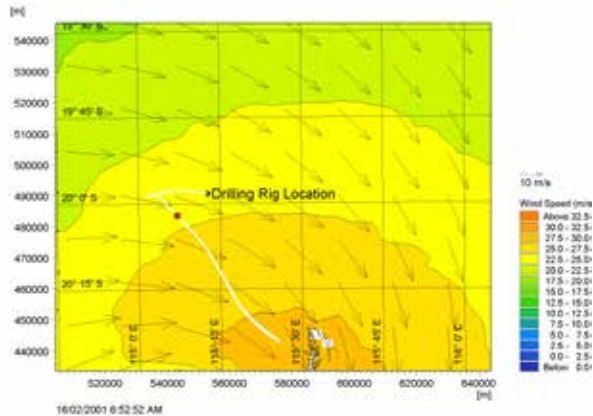


- Wind induced drift calculated stochastically based on a discrete number of controlled field drift experiments
- Derived model parameters only designed for small crafts and vessels
- No direct evaluation of vessel leeway drift
- Wave induced drift forces are either not included or simplified as function of the wind
- Full 3D hull representation is not included in response assessment

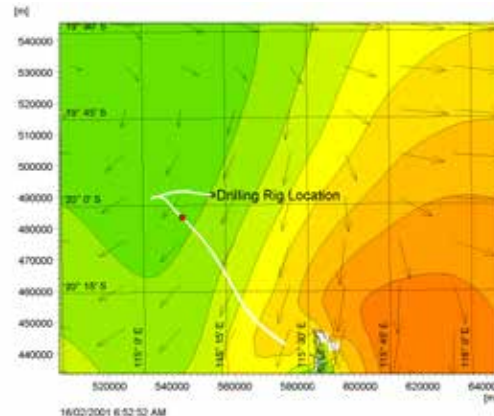
The Importance of Separate Treatment of Incident Forces



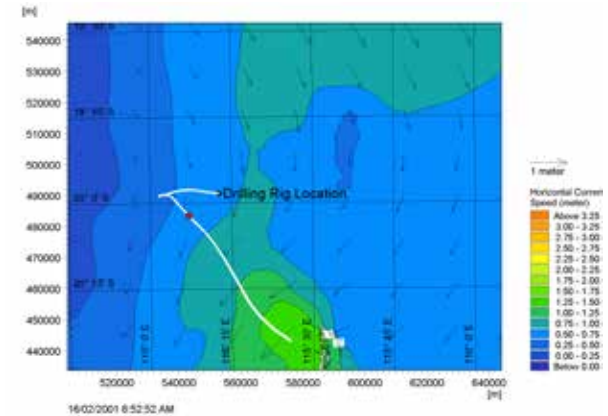
Wind Field



Wave Field



Current Field



Introducing DHIs Drifting Vessel Model (DVM)

Forces:

$$F'_{cur} = 0.5 \cdot L_{pp} \cdot T \cdot \rho_w \cdot C_{cur} \cdot u'_{cur}{}^2$$

$$F'_{wi} = 0.5 \cdot A \cdot T \cdot \rho_{air} \cdot C_{wi} \cdot u'_{wind}{}^2$$

$$F'_{wa} = 0.5 \cdot L_{pp} \cdot T \cdot \rho_w \cdot \int_{f=0}^{f=\infty} C_{wa}(f, \theta) E(f, \theta) df - Damp$$

Moments

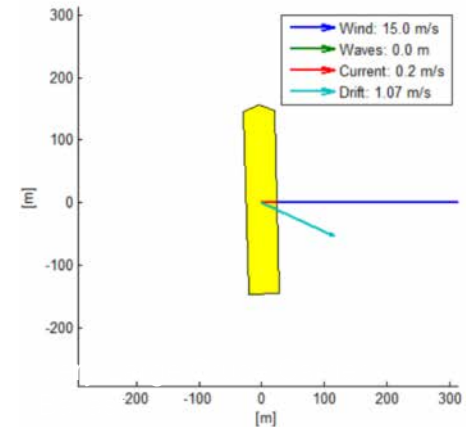
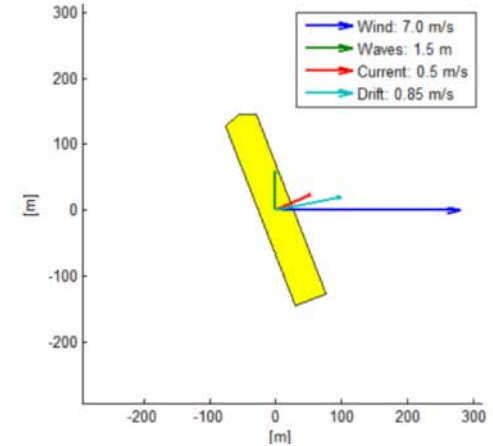
$$M'_{cur} = 0.5 \cdot L_{pp}^2 \cdot T \cdot \rho_w \cdot CN_{cur} \cdot u'_{cur}{}^2$$

$$M'_{wi} = 0.5 \cdot A_T \cdot T \cdot \rho_{air} \cdot CN_{wi} \cdot u'_{wind}{}^2$$

$$M'_{wa} = 0.5 \cdot L_{pp}^2 \cdot T \cdot \rho_w \cdot \int_{f=0}^{f=\infty} CN_{wa}(f, \theta) E(f, \theta) df$$

$$F'_{cur} + F'_{wi} + F'_{wa} = 0$$

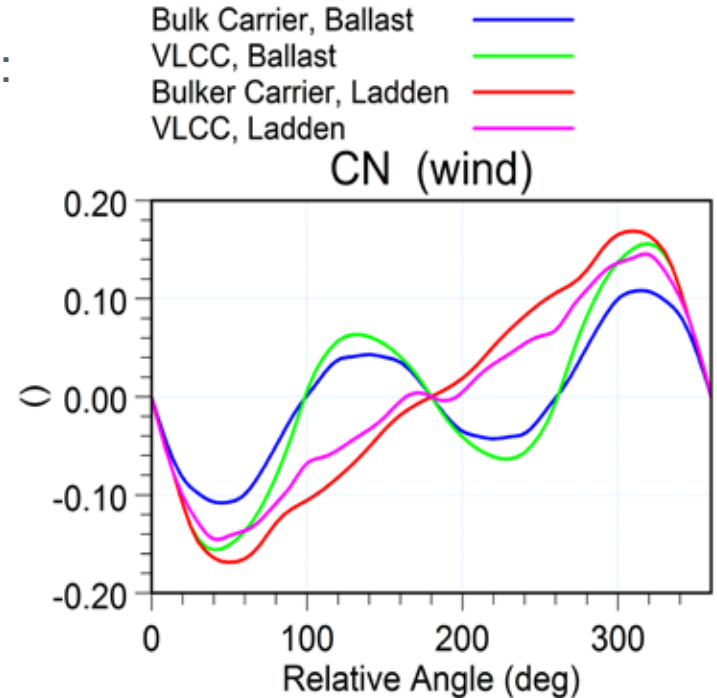
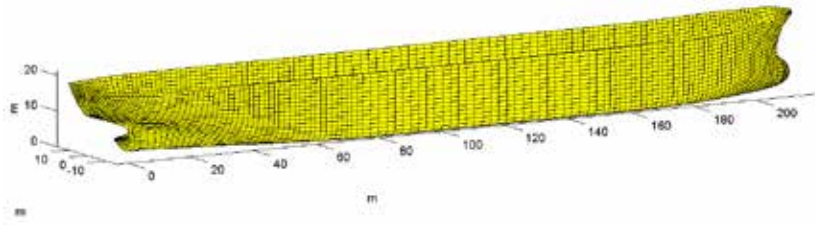
$$M'_{cur} + M'_{wi} = 0$$



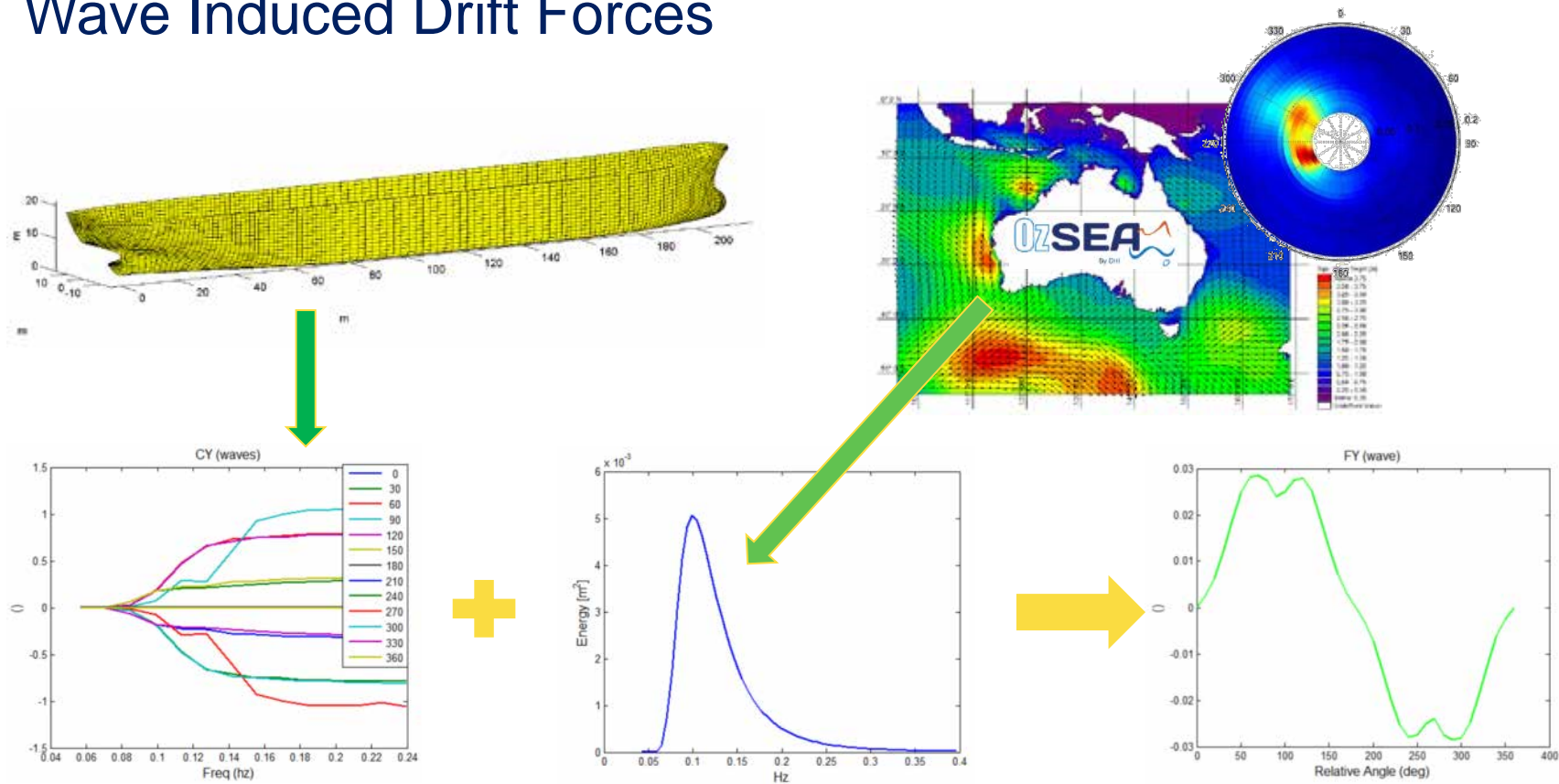
Incorporating Physical Response of Real Vessels

Vessel F_x , F_y and M_z depends on the following:

- Vessel Class
- Vessel Dimension
- Vessel Draft
- Loading Condition
- Water Depth
- Incident Wave Spectrum
- Relative Vessel Orientation
- Vessel Speed



Wave Induced Drift Forces



MIKE by DHI Integration

Drifting Vessel Model Configuration

- Stochastic Framework for Treatment of all variables and vessel modes
- Config of Vessel Modes (cruising, drifting, evading, leaking, ect)
- Interaction with other Vessels (collision)
- Interaction with domain (spilling oil, propeller wash, underwater noise)

Waves, Winds, Currents, Bathymetry



3rd Party Provider

e.g. eReef, BOM, HYCOM

Through NetCDF = DFS Conversion
(Matlab, Python)

driftingVessel.dll

ECOLAB Template
(Open Source)

MIKE ABM Lab

INPUT

INPUT

INPUT

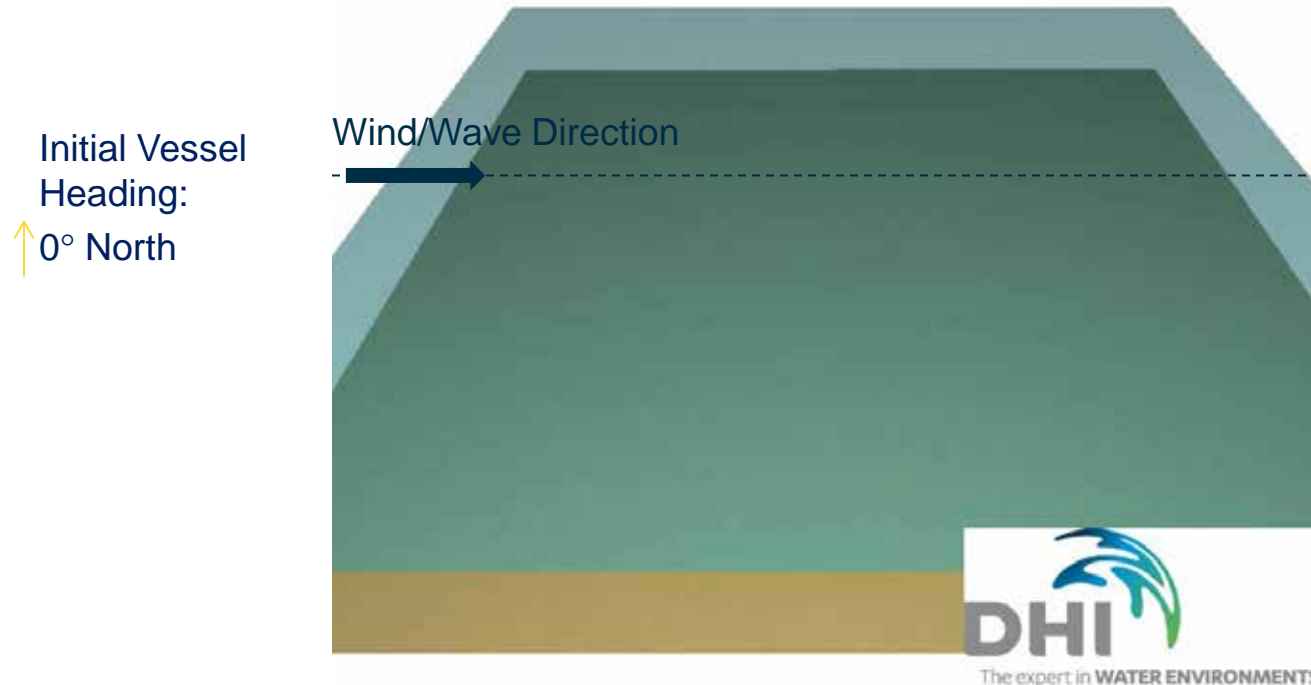
OUTPUT

Core Multiple Vessel Input(s)

- Class, Dimension
- Condition, Draft
- Initial Position and Heading
- Vessel Traffic Patterns
- Receptor Maps (e.g coral reefs)
- *Custom input Specified in Template*

- Vessel Trajectories
- Position Likelihood
- Grounding Risk
- *Customized Output*

Introducing The Hockey Puck Test



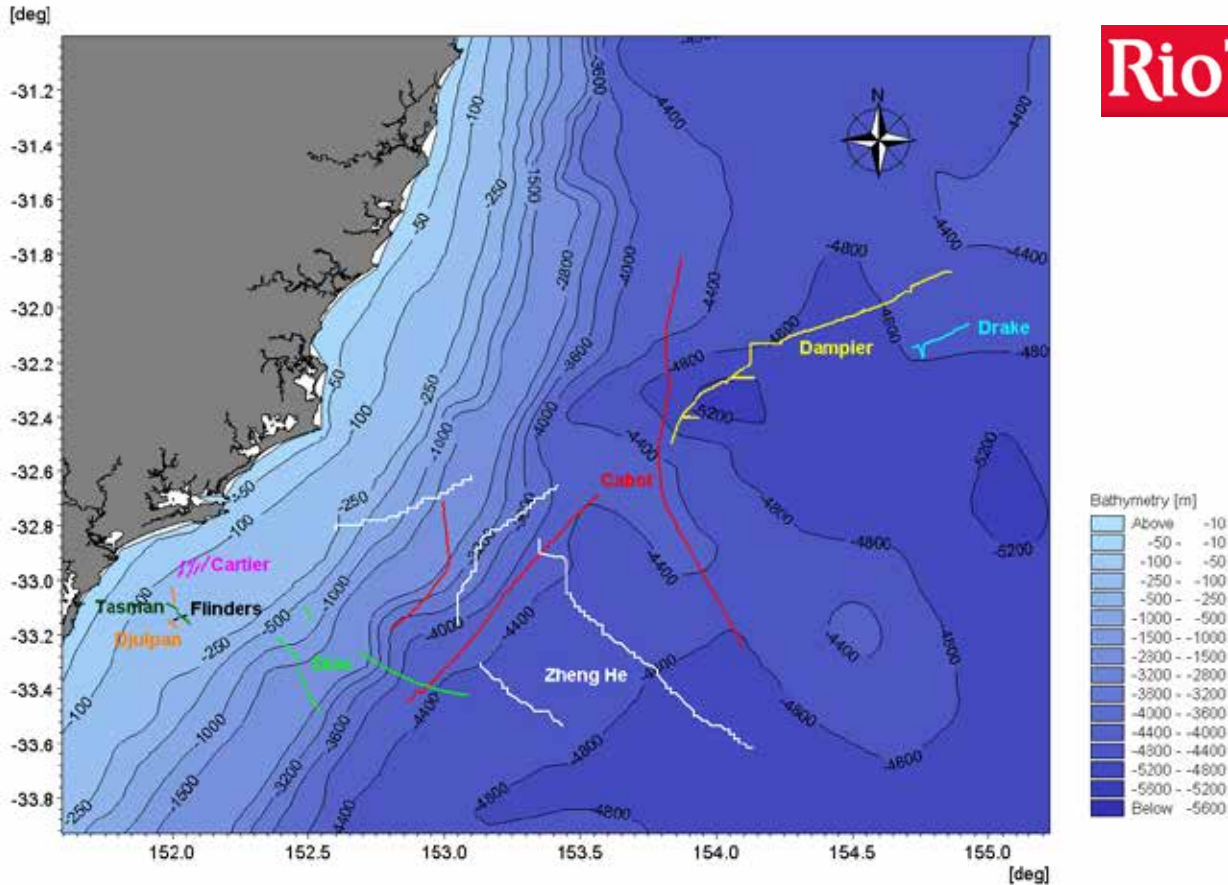
Bulk Carrier, Ballast

- No Wind, Hs: 2m, Tp: 6s, West
- No Wind, Hs: 2m, Tp: 10s, West
- No Wind, Hs: 5m, Tp: 10s, West
- 10 m/s West, no Waves
- 20 m/s West, no Waves

VLCC

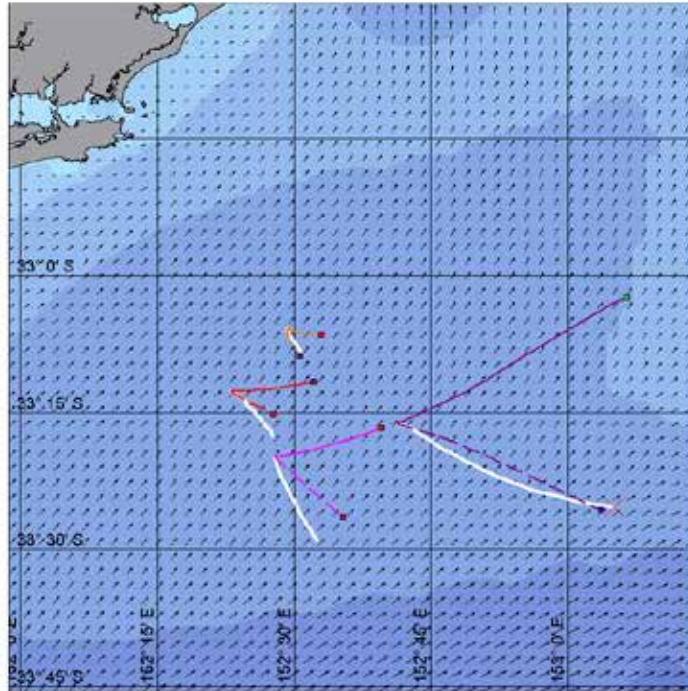
- 10 m/s West, no Waves, ballast

Overview of validated tracks (9 vessels)

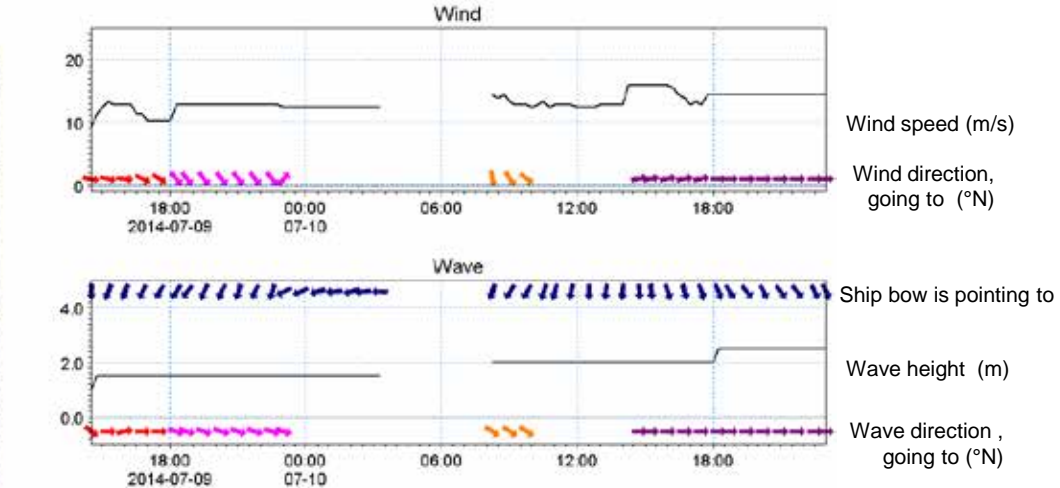


RioTinto

Vessel: RTM Dias



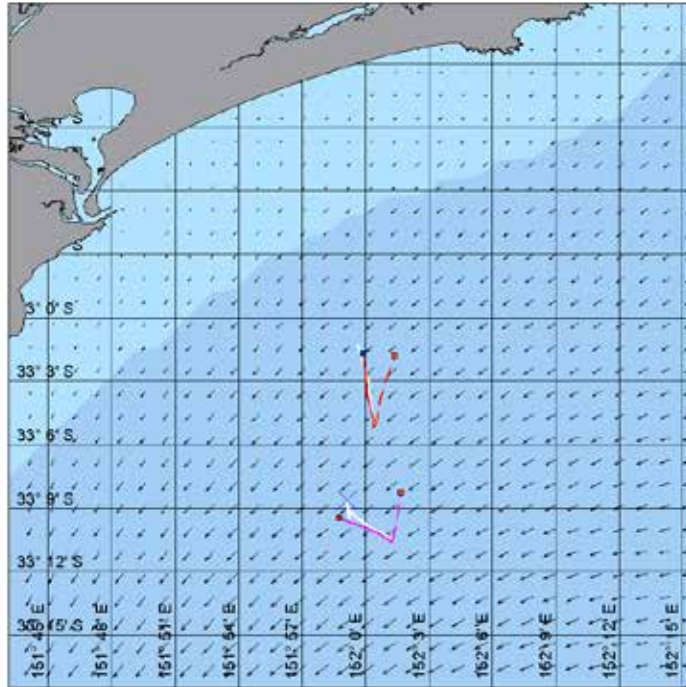
11/07/2014 4:45:00 PM



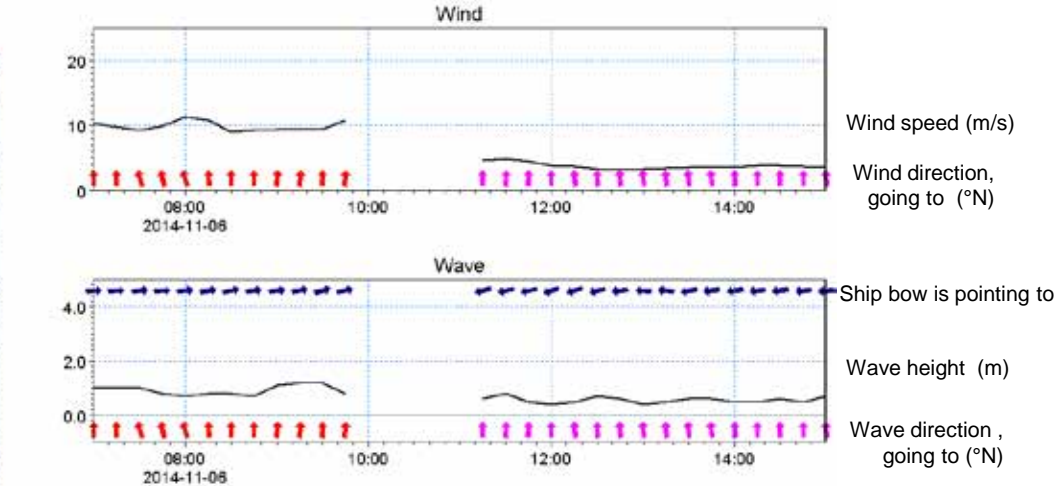
Solid line: Netwater.
Dash line: HYCOM



Vessel: RTM Djulpan



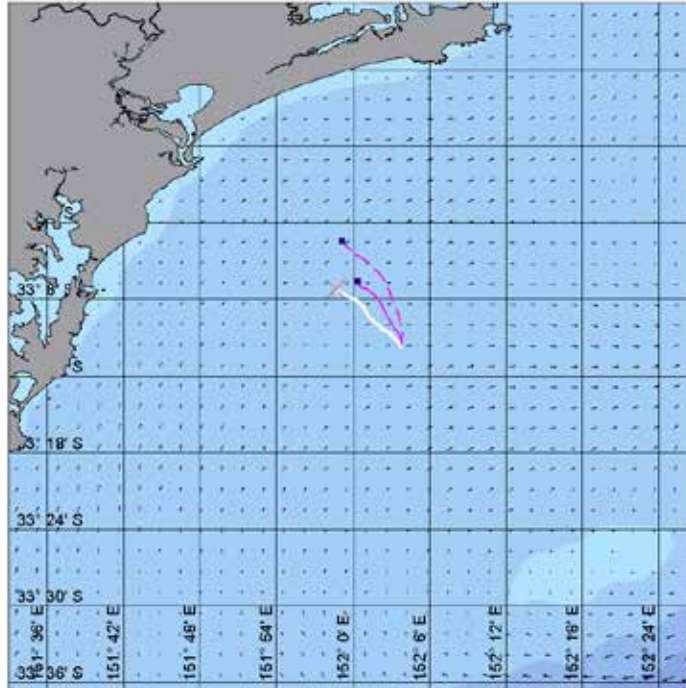
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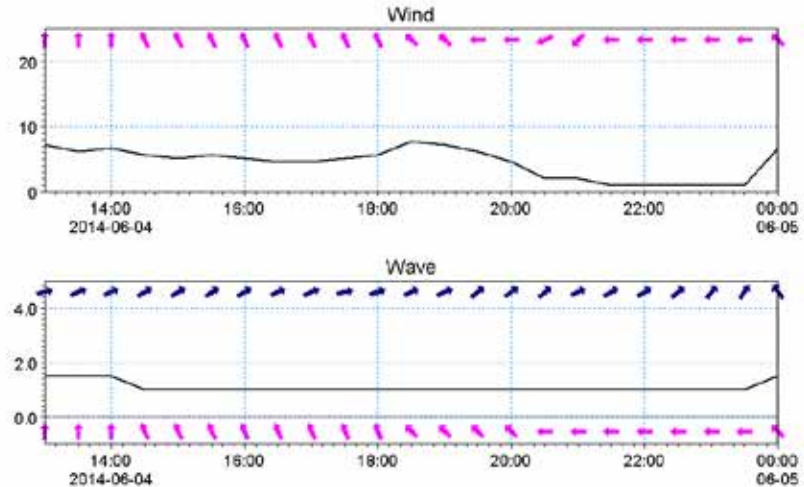
Solid line: Netwater.
Dash line: HYCOM



Vessel: RTM Tasman



5/06/2014 00:00:00



Wind direction,
going to (°N)

Wind speed (m/s)

Ship bow is pointing to

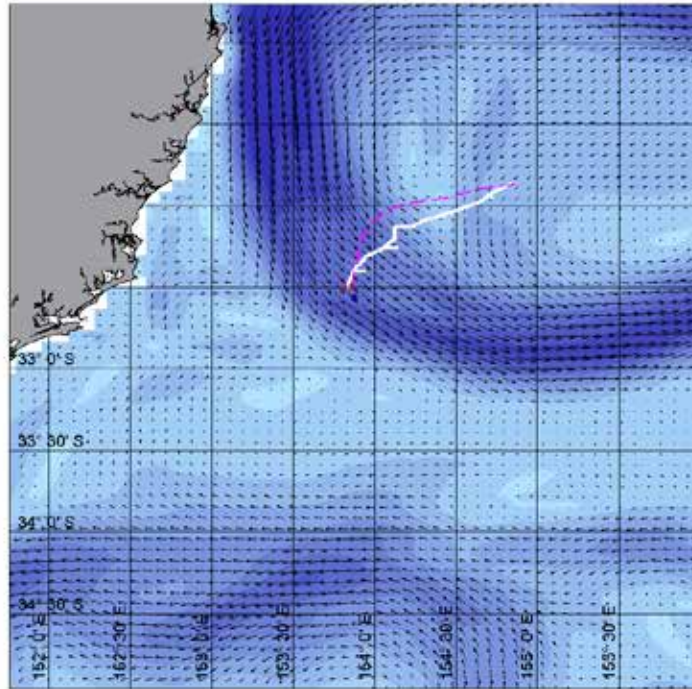
Wave height (m)

Wave direction ,
going to (°N)

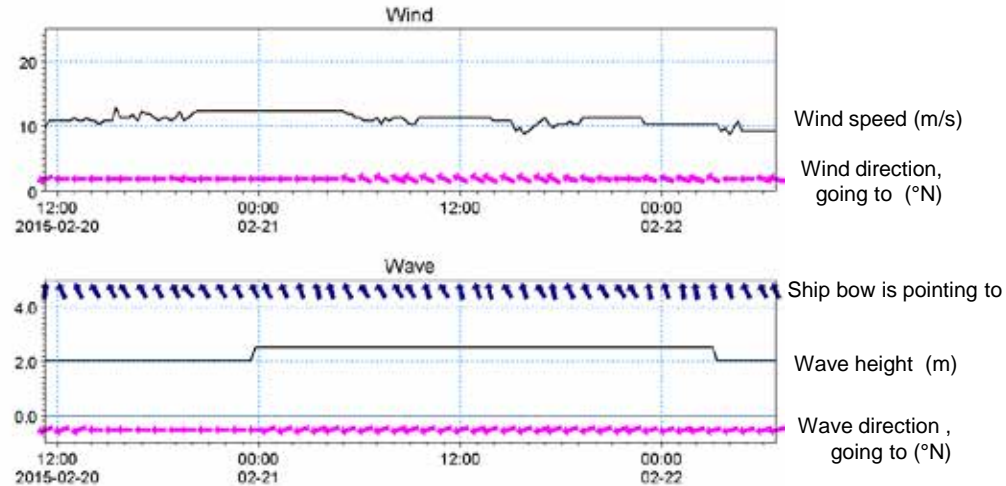
Solid line: Netwater.
Dash line: HYCOM



Vessel: RTM Dampier



22/02/2015 00:00:00



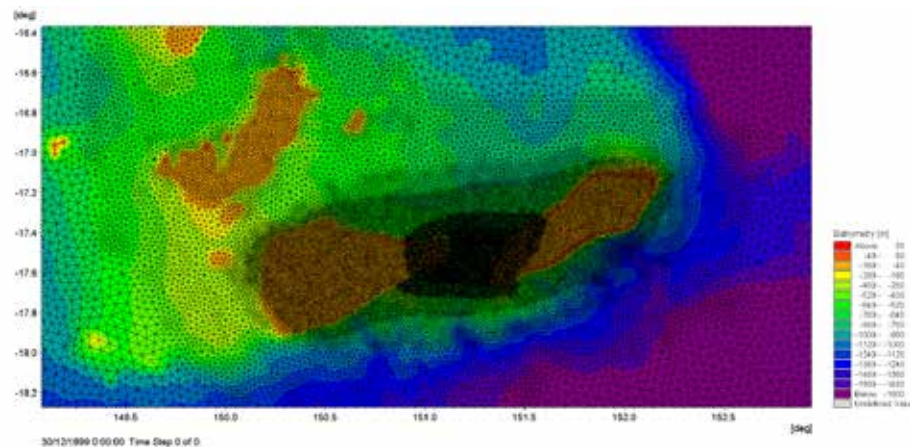
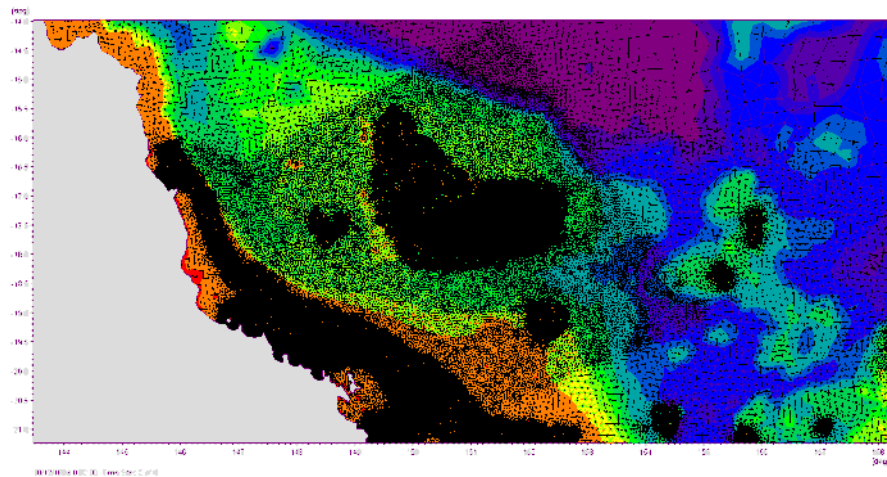
Netwater data not available.
Dash line: HYCOM



Diamond Passage – Strategic Grounding Risk – 3 year dataset

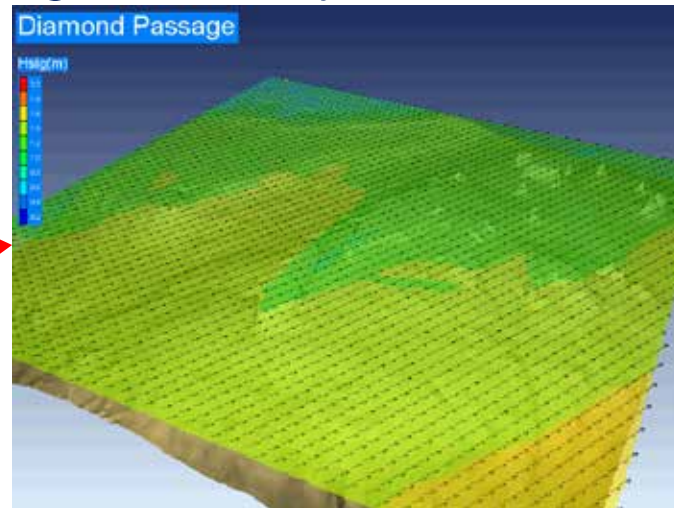
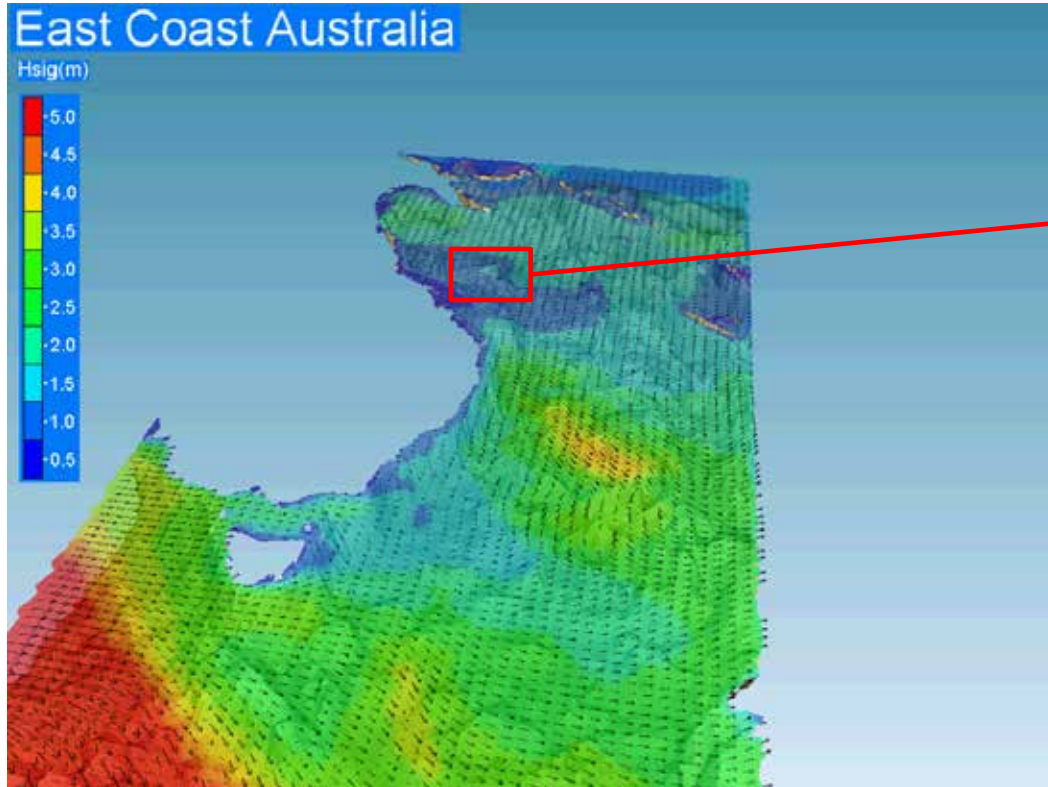
Wave Forecast/Hindcast

- **Flexible Mesh Approach**
- Detailed resolution of complex areas
- Maximum CPU efficiency



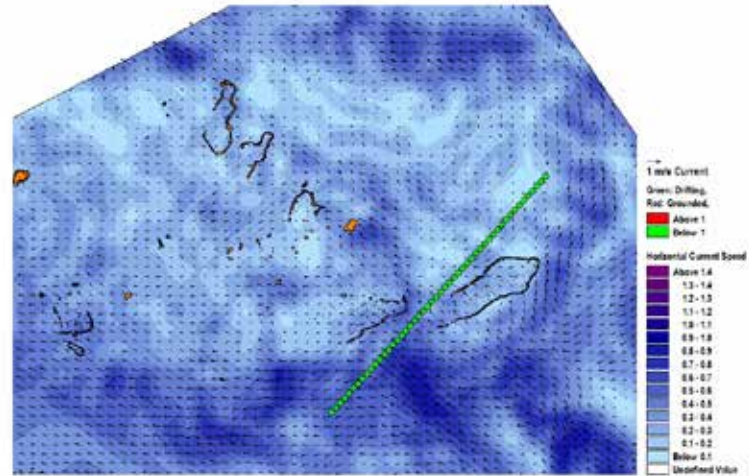
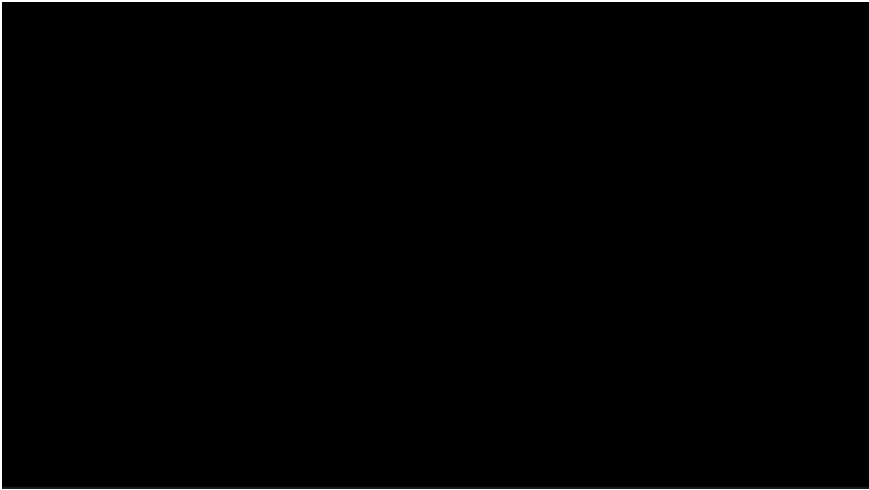
OZSEA
By DHI

Diamond Passage – Strategic Grounding Risk – 3 year dataset



OzSEA
By DHI

Diamond Passage – Strategic Grounding Risk – 3 year dataset

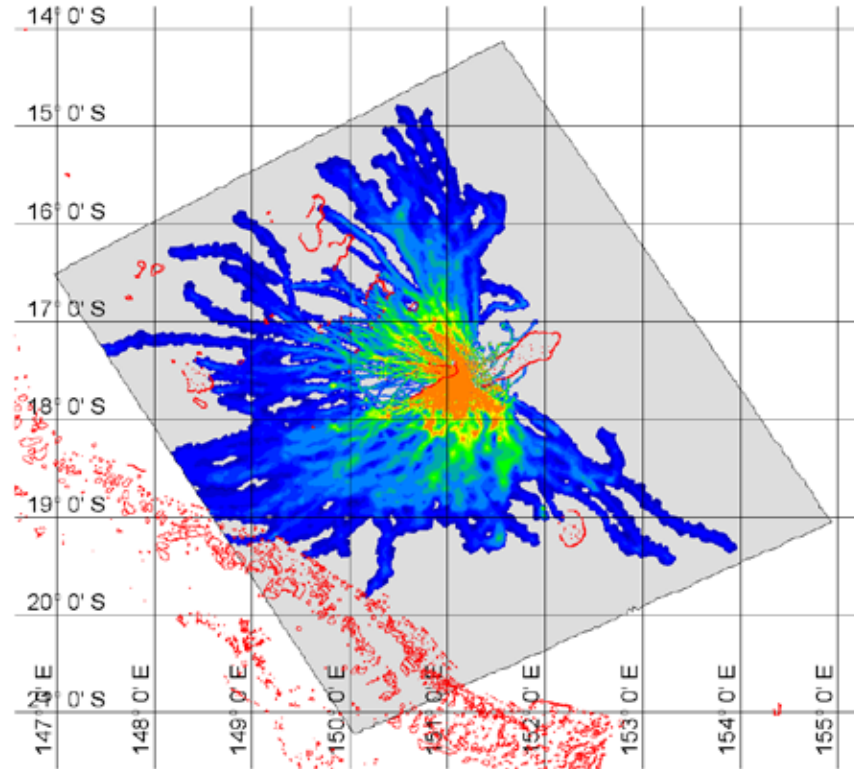


13/10/2019 0:00:00 Time Step 1182 of 2876

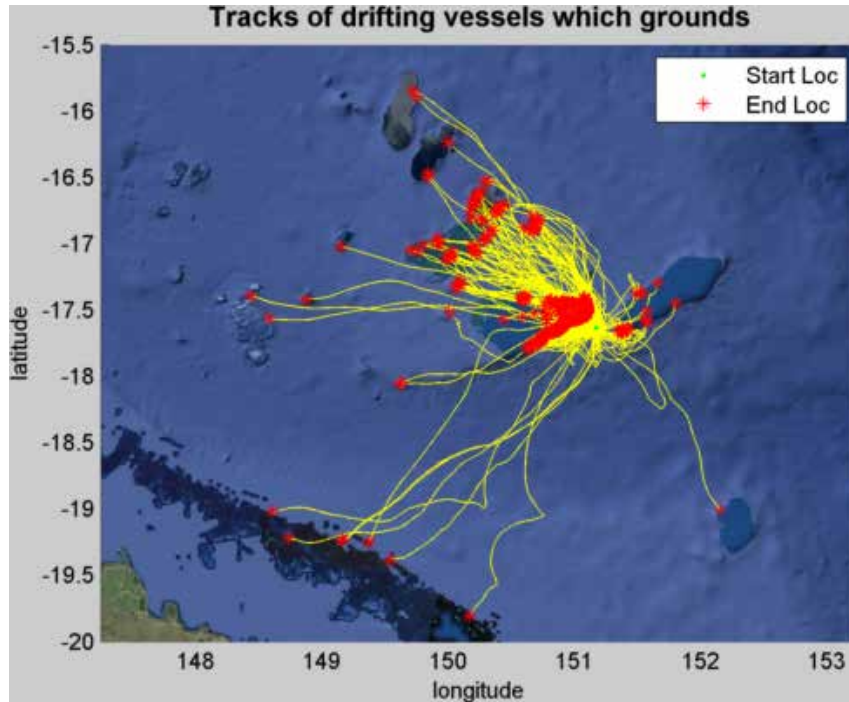


Diamond Passage – Probability Density Map

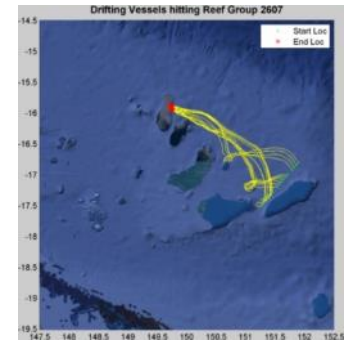
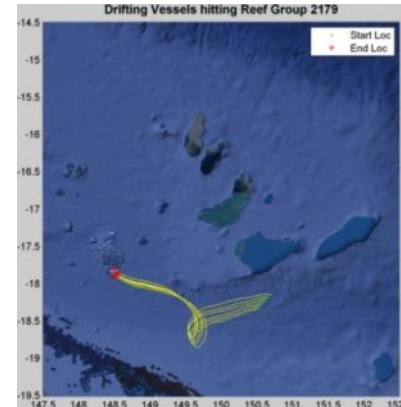
- 3 Years of historic wind, waves and currents 2011-2013
- 1019 Drifting Bulk Carriers events
- Contour plot illustrates likelihood of drifting vessel fate
- CPU time = ~6 days on a 12 core workstation



Diamond Passage – Grounding Risk

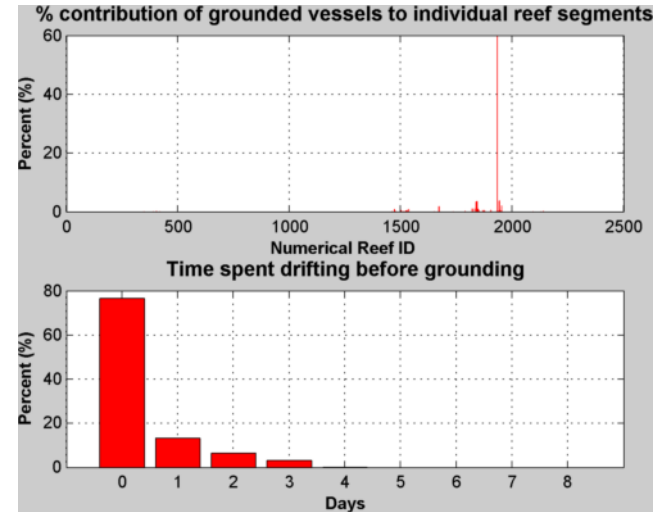


Grounding Risk Backcasting



Diamond Passage – Grounding Risk

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TextPad - C:\DHP\Projects\43800\474-AMSA Vessel Drift Forecast Model\Work\ABM\DP\Setup\DP_VesselDrift_LineSource_v4.m21fm - Result Files...
File Edit Search View Tools Macros Configure Window Help
Document Selector
Vessel2.xml
Vessel2.xml
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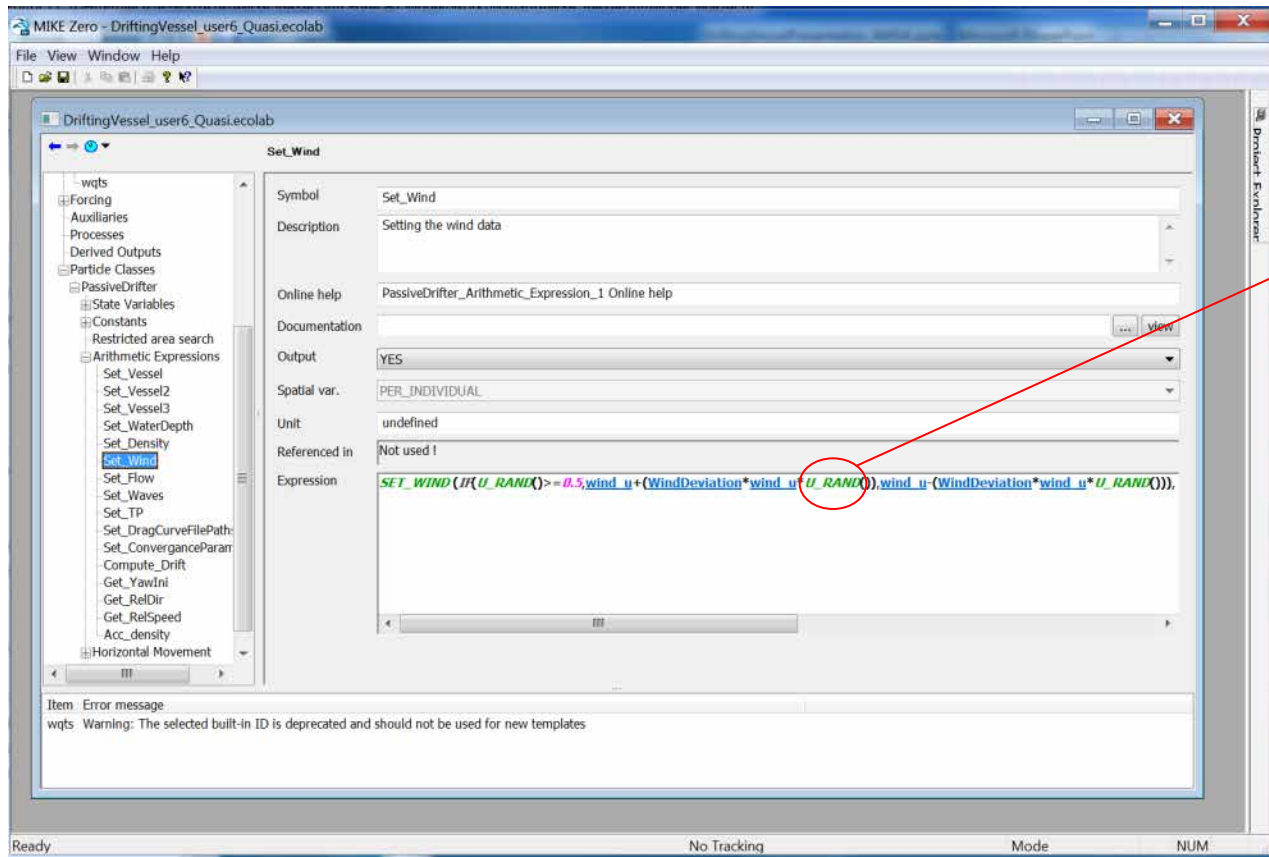
Total number of vessels grounding: 784 (out of 1019 vessels)

Number of unique reef segments hit: 76 (out of 2139 reefs in the domain)

59.8% of all grounding vessels hit Reef Segment 1933

46.9% of all vessels hitting Reef Segment 1933 grounds within 24 hours

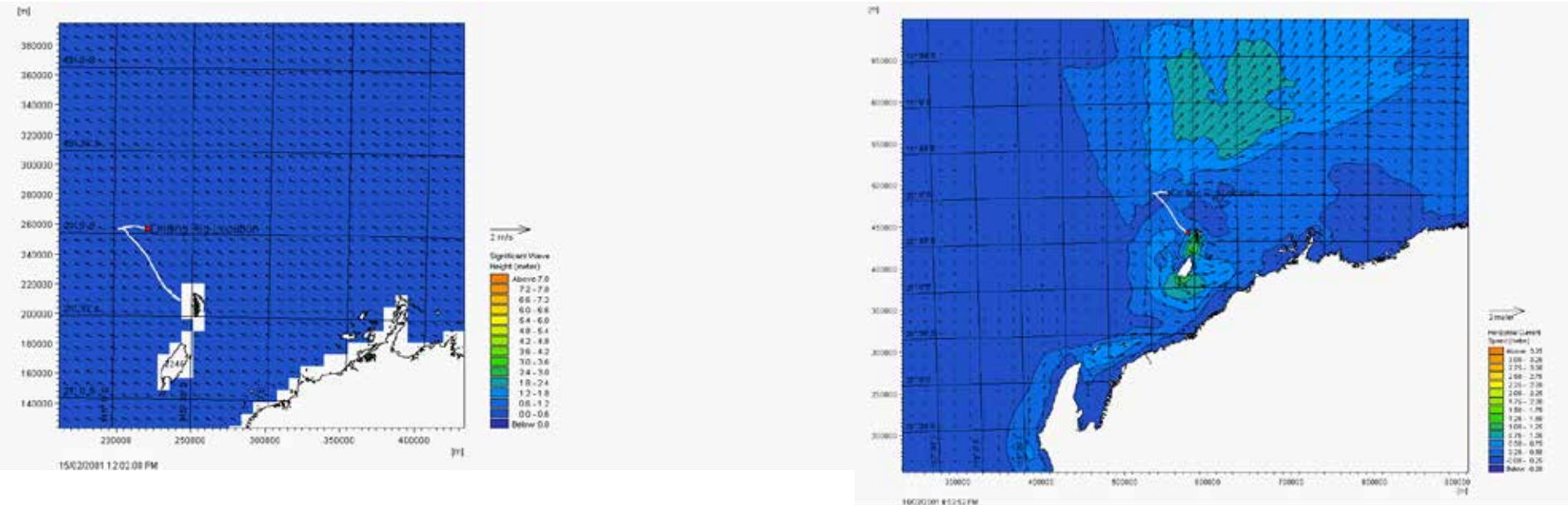
Handling of uncertainty of forcings or vessel config



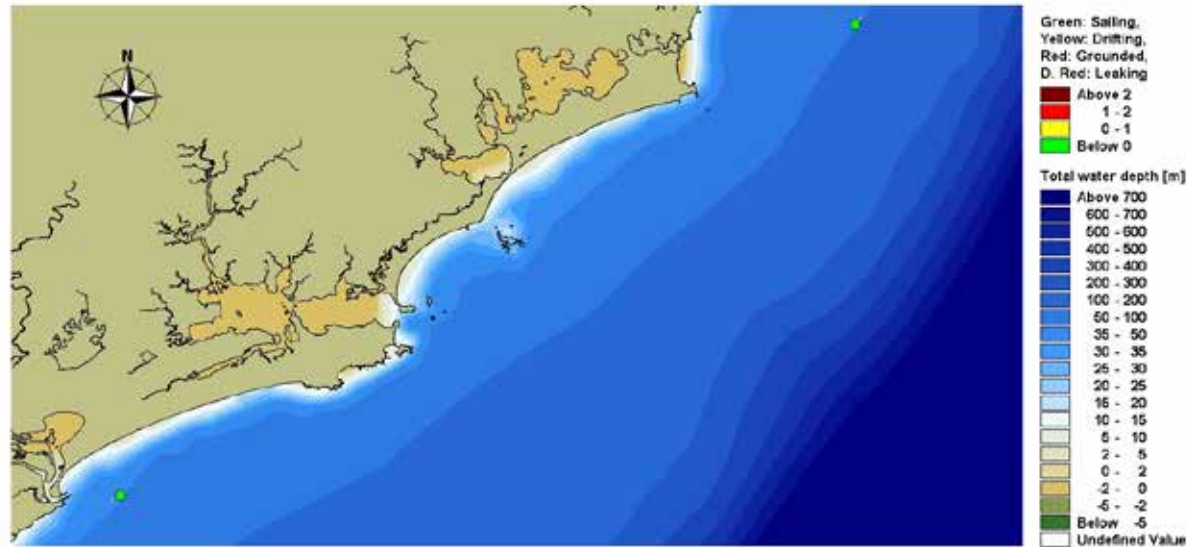
Inbuilt Probability Functions

- Uniform
- Normal
- Exponential
- Poisson
- Gamma
- Binomial

Conditional Onset of Moored Vessel Drift – Tropical Cyclones



Conditional Onset of Moored Vessel Drift – Loss of Propulsion



20/07/2014 22:15:00 Time Step 1 of 96.