US Coast Guard Search and Rescue Mission & Operational Oceanography <u>History, Model Skill, Future Work</u>

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The SAR Problem



Computer-Assisted Search Planning

CASP operational in 1974 Monte Carlo particles, LKP&Voyages, Previous Navy monthly currents 1°x1° US Navy FNOC 5°x5° winds (0,12,24,36 hr)



1984 PATHFINDER for the Great Lakes

Here in Lake Michigan

Hand enter winds Wind driven flow Teletype interface CURRENT SPEEDS IN TENTHS OF KNOTS AT 96 HOURS 3/31/19822:08 ********************** 0 1*** ****************** 0 0 0 0 2 1 1 0 ****************** 2 0 0 0 0 ************ 0 0 0 2 0 0 0 ********** 3 1 Ø*** 1 ю ************* 0 0 *** 1 *** 0 0 0 0 0 0 0 0*** 0 1 1 Ø*** *** 0 0 0 0 0 0 **** ø 1 1 0 1 ø 1 1********* 3 0 0 1 1 0 3 1 1********** 0 Ø********* 0 1 0 ø 0 0 0 0 @*********** Ø***** 1 1 1 ø 1********** ********* 1 ***** *** ø ø **** *** ø Ø Ø********************************** ю ø 0********** Ø ø Ø ø **************************** ø 1 *** 2** Ø 1 2*** ************************** 0 1 *** Й 0 1 2********************************* *** *** ø ø *** 1 1 *** 1 1 *** 2 1 1 *** 0 1 *** 1 2 ø **** 2 *** Ø********** *** ****************** *** 2 2 2 2 2 2 2***** ***** 2 2 2 2 2



Leeway in 1980's

Search Object	Leeway eq (knots) U wind in knots	Reference
PIW	0	none
Surfboards	0.02 U	Chapline (1960)
Heavy Displ. deep draft sailing vessels	0.03 U	Chapline (1960)
Medium Displ. sailboats, fishing vessels	0.04 U	Chapline (1960)
Light Displ. cruisers, Outboards, rubber rafts w/ drogue	0.05 U- 0.12 kts	Hufford and Broida (1974); and Scobie and Thompson (1979)
Large Cabin Cruisers	0.05 U	Chapline (1960)
Light Displ. cruisers, Outboards, rubber rafts w/o drogue	0.07 U + 0.04 kts	Hufford and Broida (1974)

Indirect Method

- Search Object drift over ground
 - Navigation errors: range and bearing from ship or shore, DECCA, Loran-A or –C, MTS
- Subtract Currents
 - Drift nets, dye, high flyers, drifters
 - Same navigation errors as object
 - Reset drifters around drift object
- Measure Winds
 - Ship's anemometer, on board anemometer
 - Not adjusted or adjusted (1.22 or z/10to 1/7th)
- Short records, limited to fair weather conditions

Direct Method (July 1992)



Direct Method

- Leeway measured directly by attaching selfrecording current meter
 - Long continuous 10-minute vector averaged
 - <u>Standard depth between 0.3 and 1.0 meter</u>
- Measure winds on board or from nearby craft
 Long continuous 10-minute vector averaged
 Adjusted to 10-meters
- Search Object drift & relocation
 - On board Loran-C, then GPS data loggers
 - Argos, then Iridium & RDF beacons & lights
- Long continuous records thru storms

SLDMB (Feb 1993) (Self-Locating Datum Marker Buoys) CODE/Davis surface drifters



Leeway Definition (July 1984)

"Leeway is the velocity vector relative to the downwind direction at the search object as it moves relative to the surface currents as measured between 0.3m and 1.0m caused by winds (adjusted to reference height of 10m) and waves."



20-person Beaufort life raft GPS data loggers and Argos & RDF beacons / lights

RM Young anemometer At 2.8 meters

WeatherPak



PM 1:17 DEC 4 1993

Canadian Leeway in 1990's

Type of Craft	With Drogue	No Drogue	Reference
PIW	0.0 U	0.0 U	
Surfboard	2.0% U	2.0% U	Chapline (1960)
Raft (any size)	1.3% U -0.120	1.3% U -0.120	Allen & Fitzgerald (1997)
capsized or swamped			
1 Person Raft	2.8% U-0.12	3.7% U +0.04	
4 Person Raft	2.8% U-0.12	3.7% U +0.04	
6 Person Raft	2.8% U-0.12	3.7% U +0.04	
8 Person Raft	2.8% U-0.12	3.7% U +0.04	Fitzgerald, Finlayson & Allen
10 Person Raft	2.8% U-0.12	3.7% U +0.04	(1994)
15 Person Raft	3.1% U-0.12	3.7% U +0.04	
20 Person Raft	3.1% U-0.12	3.7% U +0.04	
25 Person Raft	3.1% U – 0.12	3.7% U +0.04	
Power Boat <15ft	5.0% U -0.12	7.0% U +0.04	Hufford and
Power Boat 15-25ft	5.0% U -0.12	7.0% U +0.04	Broida (1974)
Power Boat 25-40ft	5.0% U	5.0% U	Chapline (1960)
Power Boat 40-65ft	5.0% U	5.0% U	
Power Boat 65-90ft	4.0% U	4.0% U	Chapline(1960)
Sailboat 15 ft	5.0% U-0.12	7.0% U+0.04	Hufford &Broida
Sailboat 20 ft	5.0% U-0.12	7.0% U+0.04	(1974)
Sailboat 25 to 40 ft	4.0% U	4.0% U	
Sailboat 50 ft	3.0% U	3.0% U	
Sailboat 65-75 ft	3.0% U	3.0 %U	Chapline (1960)
Sailboat 75-90 ft	3.0% U	3.0% U	
Ship 90-300 ft	3.0% U	3.0% U	

Review of Leeway – Sept 1998 (Allen and Plourde, 1999)

- Who studied what and how?
 - 95 objects from 25 studies
 - Indirect 17 studies before 1990
 - Direct 1 study in 1977, 7 studies after 1990
- How was leeway modeled?
 - Leeway Rate and Divergence Angle
 - Search Area growth related to distance from LKP
- New leeway model proposed:
 - Down and crosswind components of leeway
 - Spread according to standard error term and time
- Leeway taxonomy classes proposed.
 - Combined data sets
 - Recommended 63 leeway categories of search objects

Review of Search Theory (Jack Frost & Larry Stone 2001)

- Reviewed manual methods of search planning
 - Initially done by paper, pencil, and plotting on charts
 - Many simplifications required
 - Later automated on PCs
 - CANSARP, SARMAP, SARIS, C2PC
 - Electronic charts, tidal models
- CASP's use of Monte Carlo, Bayesian method
- USCG was using 3 SAR planning tools



Canada CANSARP





Time into Incident :0 Days 19 Hours

54.2994 , -5.2892

Leeway Divergence (Allen 2005)

- Allen and Plourde's Leeway Divergence methods
 - 2 Std Dev of Leeway angle 18 leeway categories
 - Mean + 1 Std Dev of leeway angle 9 leeway categories
 - Mean + 2 Std Dev of leeway angle 8 leeway categories
 - Visually estimated from fig 3 leeway categories
 - Assigned from other categories 25 leeway categories
- 38 of 63 Leeway categories without Down&Crosswind components of Leeway (DWL / CWL)
 - Best fit for the 25 categories with both Rate/Angle and DWL/CWL
 - Apply to 38 categories
- Now all 63 Leeway categories have DWL/CWL coefficients:
- Jibing Model (4% per hour) added.

Norwegian Met Office's 'LEEWAY' operational drift model 2002 Breivik & Allen (2008)

- Operational high-resolution ocean and met models for the Norwegian Sea
- 63 Leeway categories using DWL & CWL equations from Allen (2005)
- Jibing Model (4% per hour) added.
- Only a trajectory model, no resource planning

Map



SAROPS (Jan 2007 operational)

- Monte Carlo (2.5K, 5K, 10K particles)
- Multiple Scenarios
 - (LKP, Area, Voyage, Flare, LOB)
- 63+ Leeway categories using DWL & CWL
- Multiple Winds & Currents sources from EDS
- Optimal Search Plans
 - Lateral Range Curves of Detection on particles
- Bayesian update of previous searches
- ArcGIS based

The SAR Problem









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EDS Products (for USCG)

- 2 global met models, 16 regional met models
- 429 moored and land based met stations
- 2 Global HYCOM ocean models
- 1 global model aggregated with a tidal model
- 25 regional ocean models
- 7 tidal models
- 5 HF radar regions, 2 HF radar predictions
- 1 river flow
- 2 historical models
- SLDMBs

But, how good are the ocean models we use? Measure the Skill

By Skill at determined by Liu and Weisberg (2011)

"Evaluation of trajectory modeling in different dynamic regions using normalized cumulative Lagrangian separation" JGR, **116**:C09013



Zero currents; Skill = 0



Liu & Weisberg (2011)

Wrong way currents; Skill = -1



So, how good are the ocean models we use? An example

Hawaii, 12 FEB 2015, 150nm south of Kauai Japanese cadet lost of training vessel No model agrees with the drift of the SLDMB Used SLDMBs to generate surface current field

Skill at determined by Liu and Weisberg (2011)







Model	Percent Cover	Lifetime				6 Month				Case Start			
		Skill Score	N Bu	um oys	Track Hours	Skill Score	Nu Buo	m ys	Track Hours	Skill Score	Nur Buog	n y:	Track Hours
HFRADAR_USHI	n/a	0.0505		7	1254	0.051	5	5	997	0.0)515	5	997
STATIC	n/a	0.1699		12	2111	0.148	3	9	1500	0.1	51		1021
HYCOM_GLOBAL	n/a	0.1754		12	2073	0.166	5	9	1475	0.1	504	5	1016
HAWAII_ROMS	n/a	0.0956		7	1047	0.116	62	4	446	0			0
AGG	n/a	0.1756		12	2078	0.165	3	9	1480	0.1	163	5	1016
HYCOM_GLOBAL_NAVY	n/a	0.2195		12	2069	0.222	7	9	1470	0.2	323	5	1012



Future SAR Trajectory Work

- Ensemble Current products
 - Treat like scenarios, add particles, weight
- Use Skill
 - Order EDS products by Skill x % coverage of AOI
 - Scale Dispersion
 - Real-time verification of models
- Leeway of Aircraft debris, capsized vessels
- Model Sailboat voyages
- Numerical model of Leeway

Future SAR Optimization Work

- Detection and Sensor Performance
 - New sensors
 - New platforms (UAVs)
 - New search strategies (swarms of UAVs from ship)
 - Combine numerical modeling of sensor performance, verified by field testing results
 - Multiple sensors on a search platform
 - Time series of sensor effectiveness along SRU trackline
- Probability of Success dependent on Survival

Future Survival Work

- Models of Survival
 - Finite element models of the human
 - Post Incident Survival Web Site
 - Survival model provides probability of survival distributions to SAR planning tool.
 - Probability of Success dependent on Survival
 - Optimize on finding the survivors alive

Future Oceanographic Modeling Work for SAR

- Ensemble Models
 - Connection between models and trajectory tools
- Use Skill
 - Real-time verification of models
 - Improve models
- Output standard 1-m thick surface currents
- Capture time series of environmental data
 - From L/L point
 - From an area
 - For Survival / Detection

Challenges for SAR

- Increasing Cyber Infrastructure demands
 - Commercial upgrades of software is faster than gov't upgrades
- Increasing Cyber Security demands
 - Slows releases
 - Take an ever increasing toll
- Fewer persons lost
- Higher expectation that all will be recovered safely

Thank You

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